

In the Claims:

1     1.     (original) A method for assisting the driver of a vehicle  
2           (10) when performing a driving maneuver, a reference  
3           trajectory (16) corresponding to the driving maneuver being  
4           determined, along which the vehicle (19) is to be moved,  
5           and the steering wheel position to be set in each case and  
6           controlling the vehicle (10) along the reference trajectory  
7           (16, 19) being indicated to the driver during the driving  
8           maneuver, characterized in that, in the event of a steering  
9           angle deviation ( $d_{LW}$ ) between the actual steering angle  
10          ( $\delta_{act}$ ) actually set by the driver and the desired steering  
11          angle ( $\delta_{des}$ ) corresponding to the requested steering wheel  
12          position, the vehicle longitudinal speed ( $v$ ) is influenced  
13          independently of the driver.

1     2.     (original) The method as claimed in claim 1, characterized  
2           in that the influence on the vehicle speed is dependent on  
3           the magnitude of the steering angle deviation ( $d_{LW}$ ).

Claims 3 to 14 (canceled).

[REMARKS FOLLOW ON NEXT PAGE]